# **Rotary Clamp Cylinders - Overview**

MKRCA25

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(6)

(7) pace

8

(10) Cover

Unclamped

(Extended Position)-

L Type (Counterclock

wise Rotation)

Clamping Position

Do not clamp while the arm is rotating.

the operating range as shown below

Rotating Ar

For clamping, allow 3 mm or more before the stroke end.

<Allowable Arm Moment of Inertia:

Clamped (Retracted)

Non-rotational Accuracy

Refer to Basic Specifications

od Gasket

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iston

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# **Rotary Clamp Cylinders**



he square and space-saving cylinders have built-in rotary (swing) clamping mechanisms. Suitable for clamping small workpieces such as electronic parts in limited spaces

#### Features

- Space Saving / Square sors of all di neters (Contact / No Contact) are mountable to the cylinders.
- High Rigidity For enhanced wear resistance, the cylinders are equipped with two quide grooves compatible with all diameters.
- In addition, each of the guide pins is outfitted with a roller ( $032 \sim 050$ ).

### Basic Specifications of Clamp Cylinders

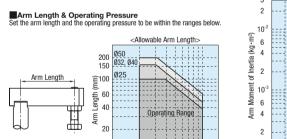
Tube I.D. (mm)		25	32	40	50
Operating Type		Double Acting			
Applicable Fluid		Compressed Air			
Max. Operating Pressure (MPa)		1.0			
Min. Operating Pressure (MPa)		0.2			
Guaranteed Withstand Pressure (MPa)		1.6			
Operating Temp. Range (°C)		-10 ~ 60 (Non-Freezing)			
Connection Dia.		M5	Rc1/8		Rc1/4
Piston Speed (mm/s)		50~200			
Cushion Mechanism		With Cushion Rubber			
Lubrication		N/A			
Rotating Angle		90°±10°			
Rotating Direction		Right / Left			
Rod Non-rotating Accuracy (when Clamped): Initial Value		±1°	±0.9°		±0.7°
Pressure Area (mm <sup>2</sup> )	Instroke Side	377	603	1055	1649
	Outstroke Side	490	804	1256	1963
Service Life		1 Million Times			

#### Stroke

Tube I.D. (mm)	Stroke	Stroke on Rotating (mm)	Stroke on Clamping (mm)	Rotating Direction	
Ø25	31	11	20		
Ø32	35	15	20	Counterclockwise	
Ø40	35	15	20	Clockwise	
050	70	20	50		

### Design / Selection

NOTE In operation, the piston rod of this cylinder strokes while rotates (at 90°). Be sure that the arm mounted onto the tip of the piston rod does not interfere with any external objects while rotating. Take precations such as installing a protective cover if the pivoting arm mounted onto the tip of the piston rod poses a hazard to human body.

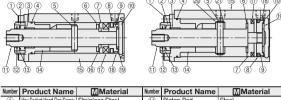


02

0.5

Operating Pressure (MPa)

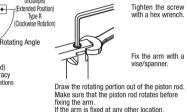
1.0



MKRCA32, 40, 50

(20) (5)





overload might damage the internal components

After tightening the screws, be sure **Tightening Torque** to retighten them at the tightening Tube Dia. Tightening Torque Arm Inertia Moment & Piston Speed 25~40 4.3~5.3N·m Set the arm inertia moment and the piston speed to be within

S

	50	10.8~13.2N•m		
Selection Example A				
<requirements></requirements>				
<ul> <li>Required Clamping Force : 500N</li> </ul>				
Operating Pressure: 0.5MPa				
Piston Speed: 100mm/s				
<ul> <li>Arm Length: 80mm</li> </ul>				
<ul> <li>Arm Inertia Moment: 2.0x10<sup>-3</sup>kg/m</li> </ul>				

1. Calculate a required pressure area Required Pressure Area (mm<sup>2</sup>)= Required Clamping Force (N) / Operating Pressure (MPa)=500/0.5=1000 (mm<sup>2</sup>). 2. Select a cylinder size based on the list and the pressure øraa (instruke side).
 Ø40 Pressure Area: 1055 (mm<sup>2</sup>) > Required Pressure Area 1000 (mm<sup>2</sup>) 3. Make sure that the arm length and the operating pressure are within the operating ranges as shown in the applicable chart.

Operating Pressure 0.5MPa - Arm Length 80mm: Within the Operating Range 4. Confirm that the arm inertia moment and the piston speed are within the operating ranges as shown in the chart. Lever Inertia Moment 2.0x10<sup>-3</sup>kg/m-Piston Speed 100mm/s: Within the Operating Range

100 Piston Speed [mm/s] Note)The Arm Allowable Inertia Moment Chart applies only to vertical actuation installations

Operating Ran

200

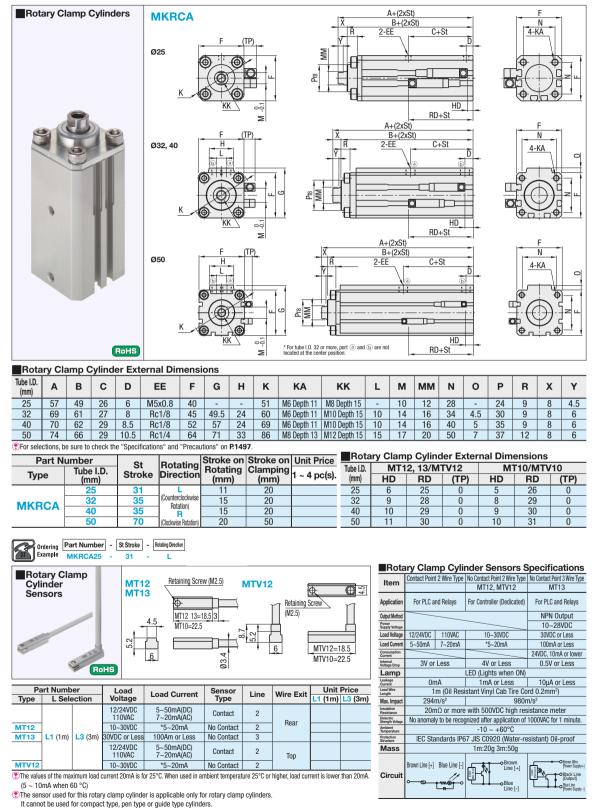
	484.
(Rotary Clamp Cylinders) A CAUTION	
Never touch any moving part while the cylinder is in operation. It is extremely dangerous because fingers may be caught between moving parts.	

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(Rotary	ClampC	vlinder	NOTE

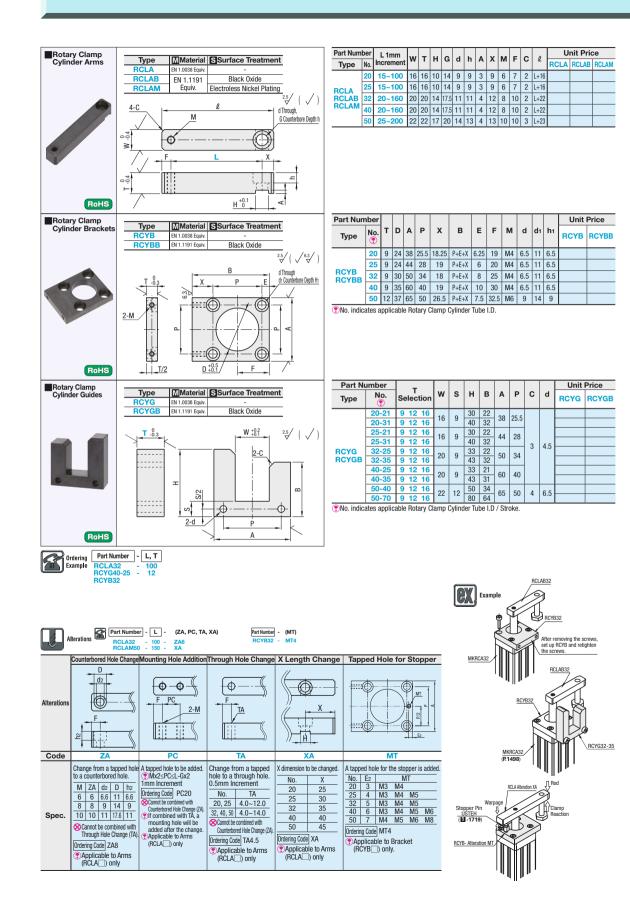
(Rotary ClampCylinder) A NOTE	
① Protect the sliding sections of the piston rods and piston guide rods from being scratched and dented.	(5) Flushing
<ol> <li>Installing the Speed Controller</li> </ol>	Before plumbing, flush the pipe thoroughly to protect it from solids or seal tape fragments.
Install the speed controller (meter out: throttle on the exhaust side) to the air pressure outlet side.	6 Ambient Environment
The performance of the speed controller affects the operation of the cylinder.	Do not use the cylinder in the following environments:
Use a speed controller with low cracking pressure.	An area filled with oil or grease. (It may cause dust to adhere to the sliding section.)
③ Installing Conditioning Equipment	An area where intense vibrations may occur.
Cylinder failures are mostly caused by foreign materials in the atmosphere or drains.	An area where the equipment may be affected by chemicals.
Protect the cylinder from trouble by installing an air dryer or air filter upstream.	
(4) Space	
Provide sufficient space around the equipment to ensure easy handling.	



Part Number

# **Rotary Clamp Cylinder Arms / Brackets / Guides**

# **Compact Parallel Grippers - Overview**



#### Compact Parallel Gripper - Features

- These are lightweight and compact, as well as achieving the high-rigidity and high gripping forces · High gripping repeatability leads to less gripping errors.
- These can be used with the fingers, which are easy-to-select depending on column, cylindrical or square workpiece shape.
- The fingers can be mounted to the main body directly, having more freedom for designing
- •By installing attachments (optional), it can be mounted with the same
- mounting method with the guide-integrated type Pneumatic Grippers. Selection Guide

## Selection Procedure

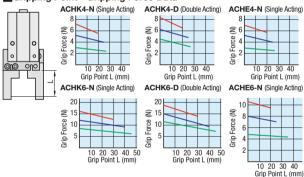
- ①Confirmation of Conditions: Confirm the necessary open/close stroke. workpiece weight and shape.
- (2) Calculation of Required Gripping Force: The required gripping force should be 10 to 20 times of the workpiece weight. (When high acceleration, deceleration or impact load may occur, higher multiplier should be selected.) (3) Selection of Types: The aripping forces are different by aripping methods (External Grip / Internal Grip), gripping point distance and operating pressure depending on types. Select the appropriate model from the Gripping Force Chart.

#### Precautions for Selection

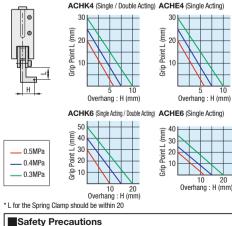
- Design the Finger Attachments to be lightweight and short.
- Set the overhang under the limit of specified value of each product type.

Lateral overhand loads will apply torsional moments on the sliding components and it may cause premature wear

#### Gripping Point - Gripping Force Data



### Gripping Point - Overhang Data



### Danger

- Do not use the cylinder for the following applications: 1. Medical Equipment for Sustaining Human Life or Maintaining the Human Body 2. Systems or Machine Equipment for Moving or Transporting Humans, 3. Vital Parts of Machinery. These products are not designed to be used for purposes requiring high levels of safety. Loss of human life may result.
- Do not use in locations with dangerous combustible or flammable objects. The objects may ignite or catch fire. Never modify the products. It may cause injury, electric shock or fire by abnormal operations. Avoid inappropriate dismantling or re-assembling of the products which affect the basic structure, performance or functions

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🖲 Do not splash water on the products. If the products are made wet, washed or used in the water, they may cause injury, electric shock or fire by abnormal operations.

Performance

Stroke Accuracy 0~0.3mm

Specifications

Operating Pressure Range 0.3~0.5MPa

Ambient Temperature 5 ~ 50°C

Stroke Tolerance 0~+0.3mm

Repeatability

±0.01mm

npared to the same size

Operating Method Single and Double Acting / Parallel Open/Close

Applicable Fluid Clean Air (Filtered, Compressed Air)

Operation Speed (max) Single Acting 120CPM / Double Acting 180CPM

\* For ACHE Type, only Single Acting Type is available. \* The operation speed of ACHE Type is Max.180CPM.

Pneumatic Fitting M3x0 5 (ACHE: M5x0 8)

+0.01mm

ufacturers: Approx. 2 times

100 Million Open/Close Cycles

with 6mm dia. and ACHK4 (Research by MISUMI)

Repeatability

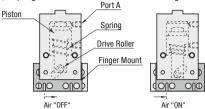
Gripping

Force

Non-load Durability Test

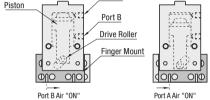
#### Open/Close Operation

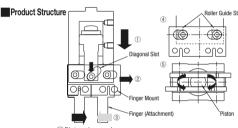
#### Single Acting Type When the air enters the Port A, it presses the piston, and the drive roller presses the finger mount to slide. When the air is released from Port A, a spring mechanism causes a return to the original state.



### **Double Acting Type**

When the air enters the Port A, it presses the piston, and the drive roller presses the finger mount to slide. When the air enters Port B, a return to the original state occurs. Port A





DPiston descends. 2)The diagonal slot moves to the arrow direction. 3 Fingers (Attachment) close. (4)2 rollers quide the cylinder movement 5) The niston rotates when moving forward and back and presses the finger mount onto the inner wall of the cylinder. The clearance will be locked up by this mechanism.

### How to Grip

